

<u>A</u>DHERENT <u>C</u>ELL <u>T</u>HERAPY USING <u>SMART</u> ROBOTICS INTRODUCING ACT SMART

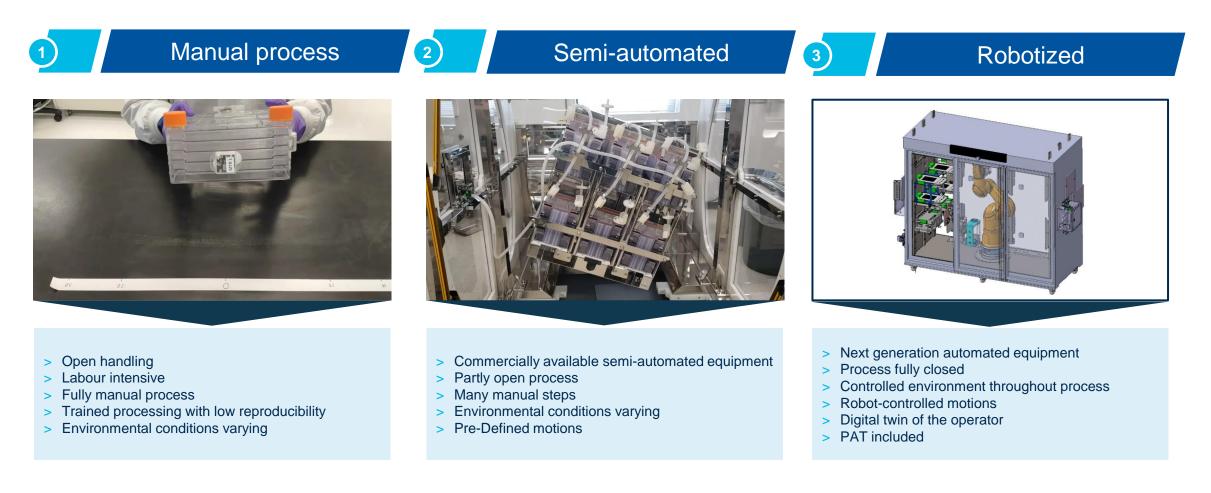
JAN CHRISTIAN HEIDENREICH SUBASH RAMAMOORTHY JENS TRÄNKLE MARIUS KLING

RAYA 2023 Finalist Event



What is the use case?

Towards Industrialization of Cell Therapy Manufacturing





Why is it smart?

Adherent Cell Therapy using Smart Robotics

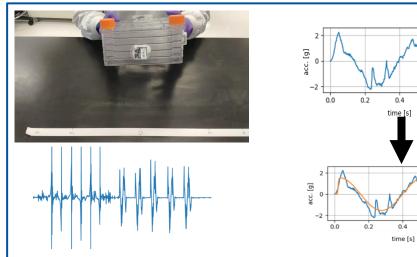




Robotic Cellstack handling



Sensing and Recording



Modeling and Translating

Motion Model Implemented



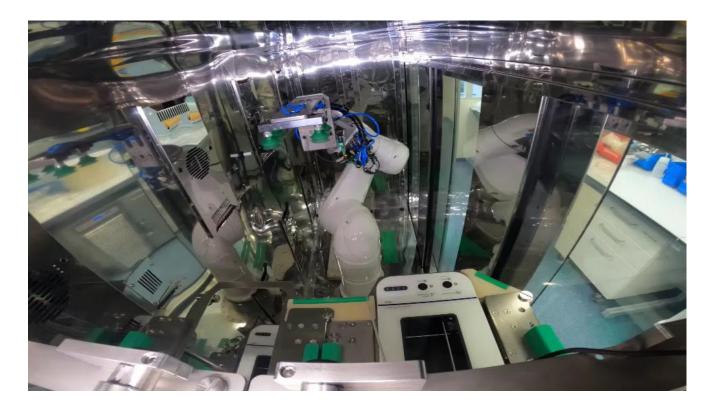
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0.6

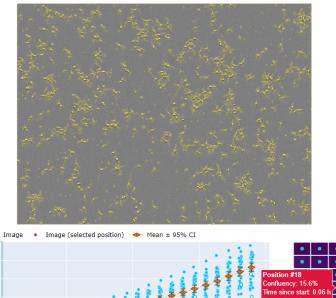
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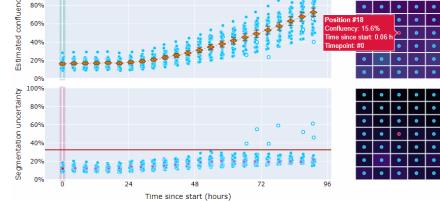
What is the result?

<u>A</u>dherent <u>C</u>ell Therapy using <u>Smart</u> Robotics



Automated Processing





Automated real-time Monitoring

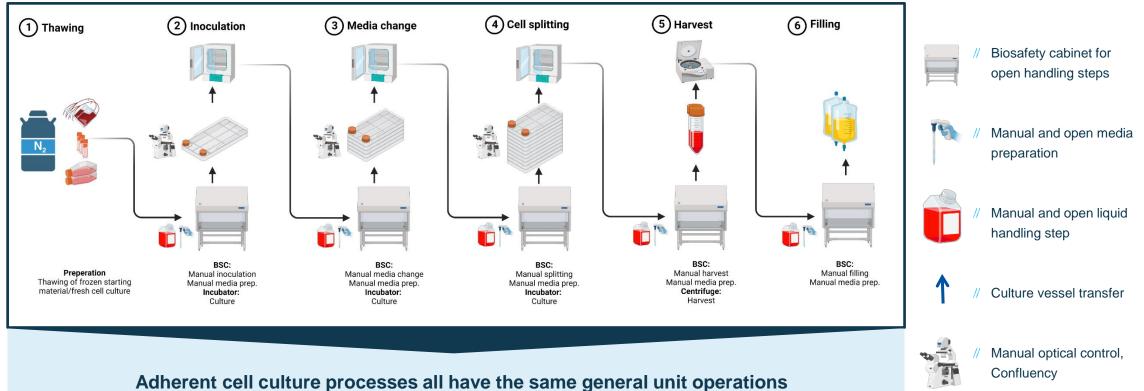


Knowledge

100%

Flexibility, area of application and drivers

Generic Manual Process for 2D Stem Cell Cultivation & Differentiation



 \rightarrow Differences: Process workflows and parameters within the unit operations

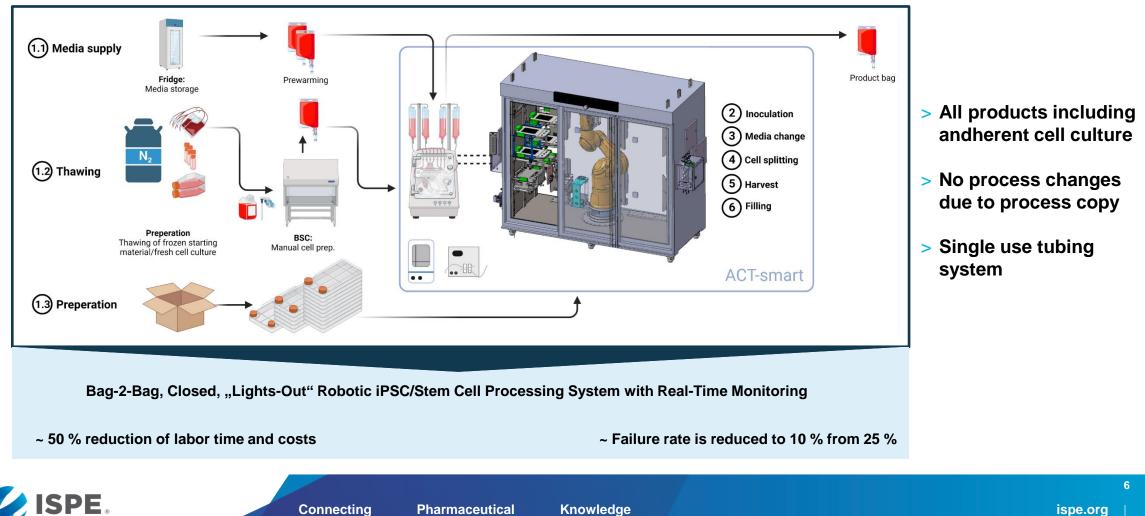


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Flexibility, area of application and drivers

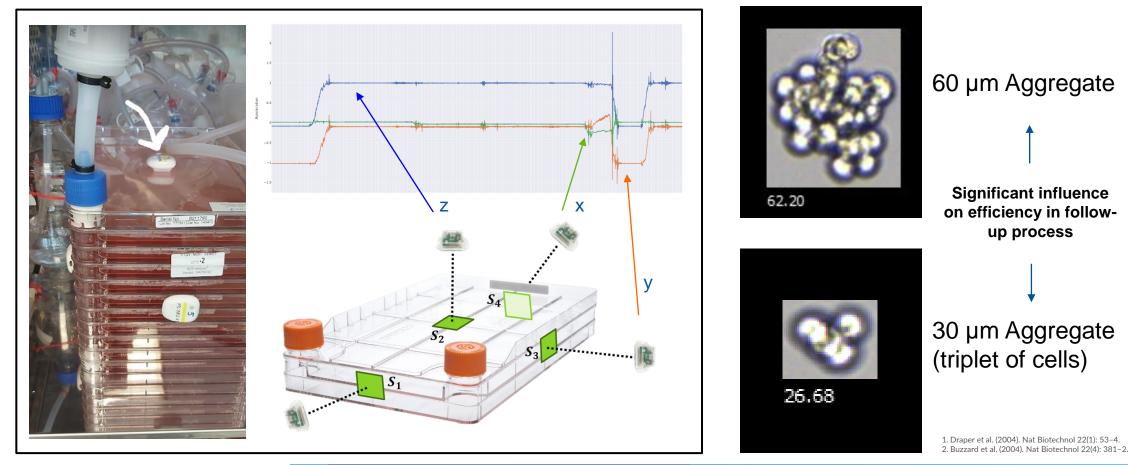
Generic Automated Process for 2D Stem Cell Cultivation & Differentiation



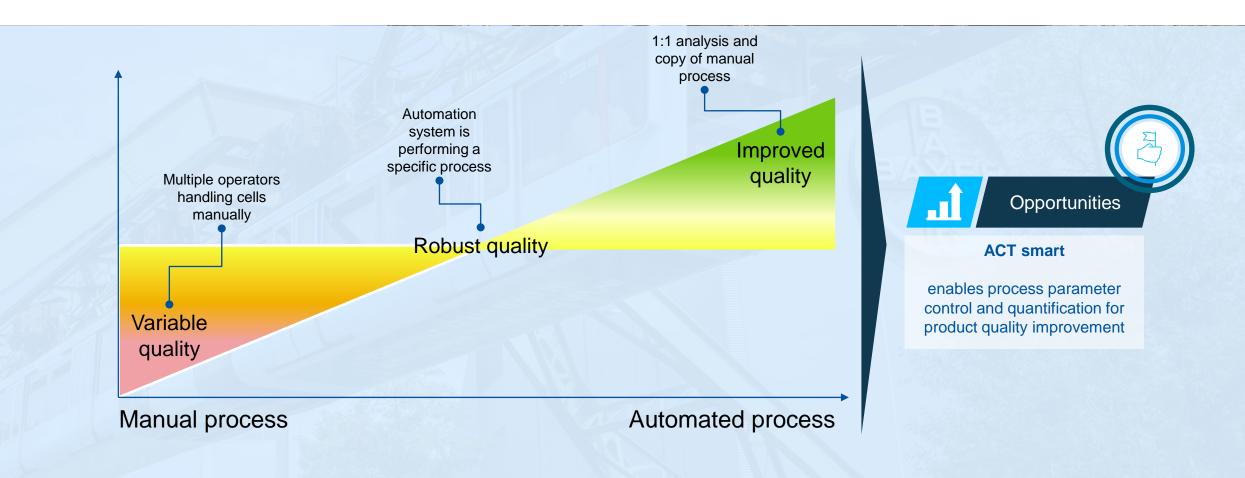
2 Features

"Power Input" is an Important Parameter for "Clump Passaging"^{1,2}

Controlling the forces applied during the cell dissociation process (as a Process Parameter) allows the selection of the right clump size



Beyond robustness, automation enables more process control for new modalities from Cell & Gene Therapy







VIELEN DANK! THANK YOU!

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